

GAN Prior based Null-Space Learning for Consistent Super-Resolution

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Outline

- Authorship
- Background
- Method
- Experiments
- Conclusion

Background

Noise-free Image Restoration



x



$y = Ax$



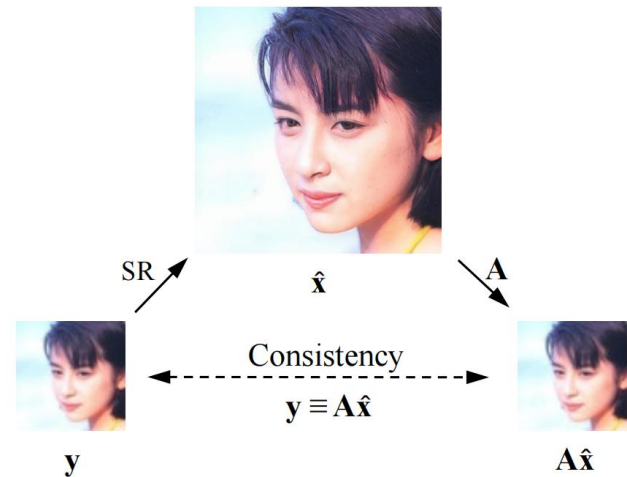
$\hat{x} = A^{-1}y$

Background

Noise-free Image Restoration

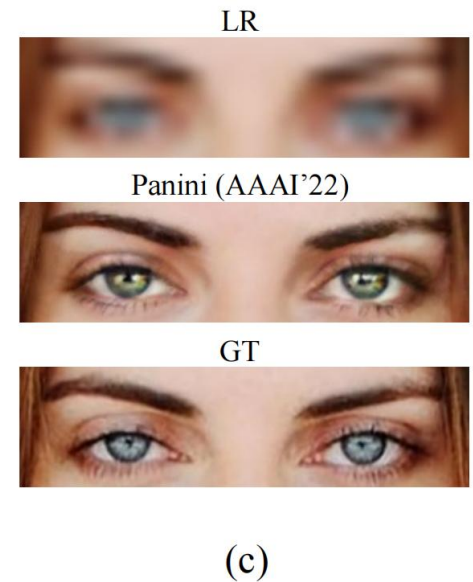
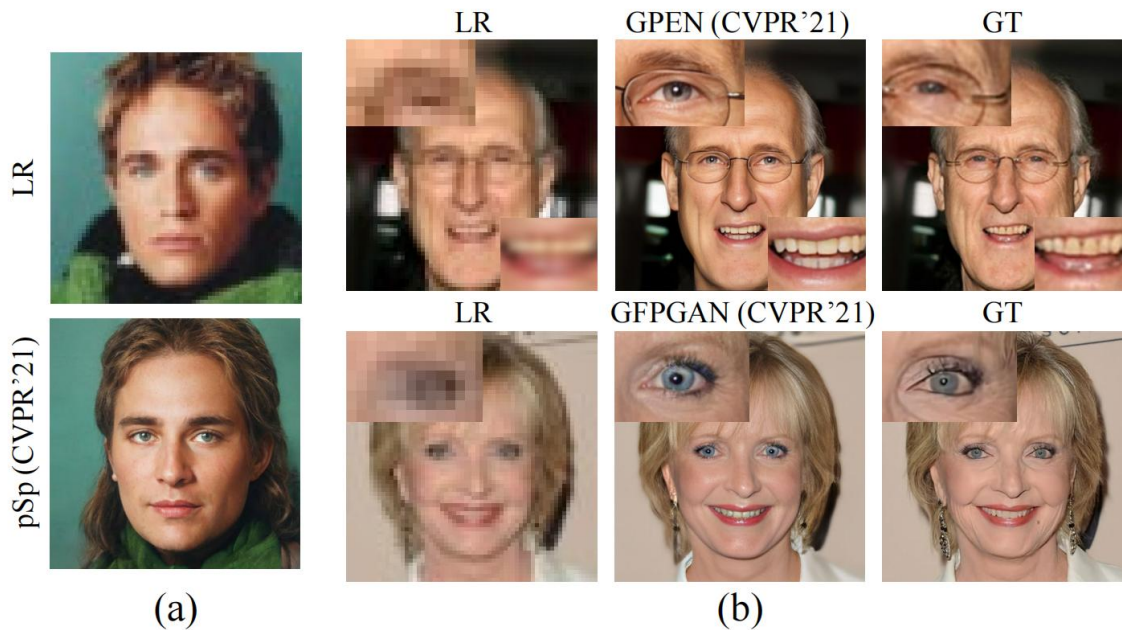
Consistency: $y \equiv \mathbf{A}\hat{x}$

Realness: $\hat{x} \sim p(x)$



Background

GAN-based SR



Background

Range-Null Space Decomposition (RND)

given a non-zero linear operator \mathbf{A} , it usually has at least one pseudo-inverse \mathbf{A}^\dagger that satisfies:

$$\mathbf{A}\mathbf{A}^\dagger\mathbf{A} \equiv \mathbf{A}$$

It can be obtained by SVD.

Background

Range-Null Space Decomposition (RND)

$\mathbf{A}^\dagger \mathbf{A}$ be seen as the operator that projects samples to the range space of \mathbf{A} , since $\mathbf{A} \mathbf{A}^\dagger \mathbf{A} \equiv \mathbf{A}$. While $\mathbf{I} - \mathbf{A}^\dagger \mathbf{A}$ can be seen as the operator that projects samples to the null-space of \mathbf{A} , since $\mathbf{A}(\mathbf{I} - \mathbf{A}^\dagger \mathbf{A}) \equiv \mathbf{0}$.

Background

Range-Null Space Decomposition (RND)

$$x = \mathbf{A}^\dagger \mathbf{A}x + (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A})x$$

range space *null space*

Method

In real world, \mathcal{X} is unknown.

$$x = \mathbf{A}^\dagger \mathbf{A}x + (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A})x$$



$$x = \mathbf{A}^\dagger y + (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A})\hat{x}_r$$

Method

In real world, \mathbf{A} is unknown.

“We observe that many downsampling methods with antialiasing share very similar results.”

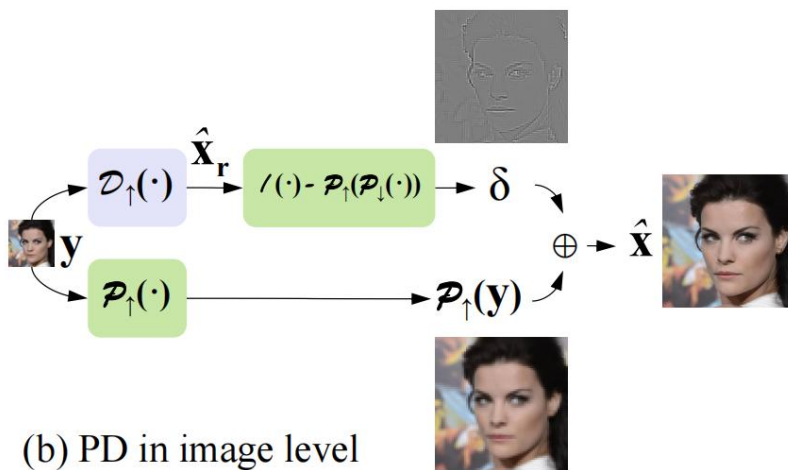
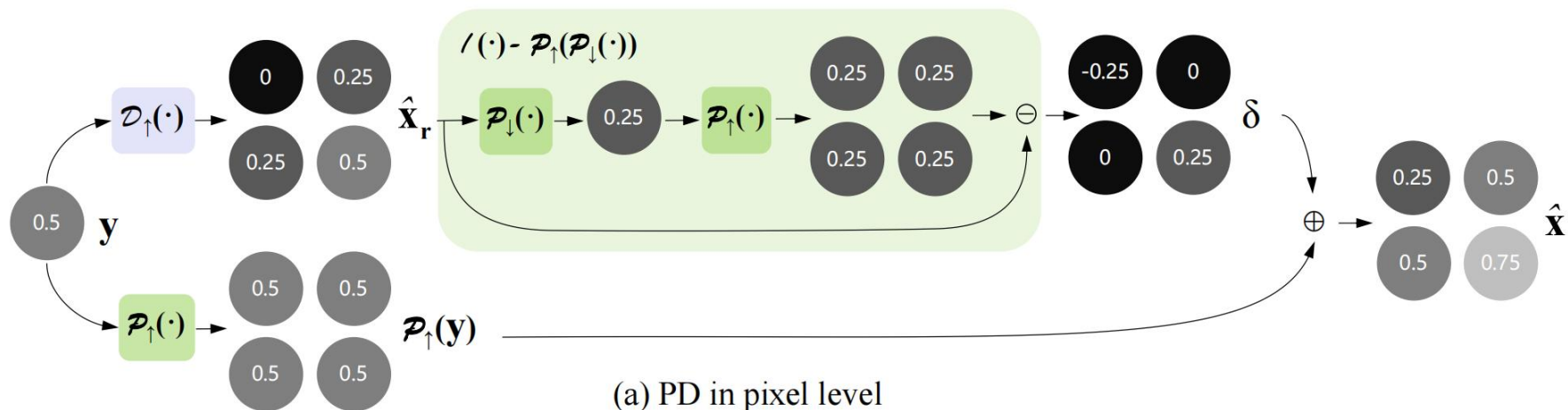
$$x = \mathbf{A}^\dagger y + (\mathbf{I} - \mathbf{A}^\dagger \mathbf{A}) \hat{x}_r$$



Pooling-based Decomposition

$$x = \mathcal{P}_\uparrow y + \hat{x}_r - \mathcal{P}_\uparrow \left(\mathcal{P}_\downarrow \left(\hat{x}_r \right) \right)$$

Method



Experiment

Comparison with CEM [CVPR22]

$$\mathbf{A}^\dagger = \mathbf{A}^T (\mathbf{A}\mathbf{A}^T)^{-1}$$

Method	PSNR(LR) \uparrow	Time \downarrow
CEM	42.2	31.8ms
PD	145.7	0.68ms

Table 1: **Validation of the *consistency*.** To compare PD with CEM, we calculate the *consistency* strictly following their theories, respectively. The result shows that the implementation of PD is faster and more precise.

Experiment

8x and 16x human face SR

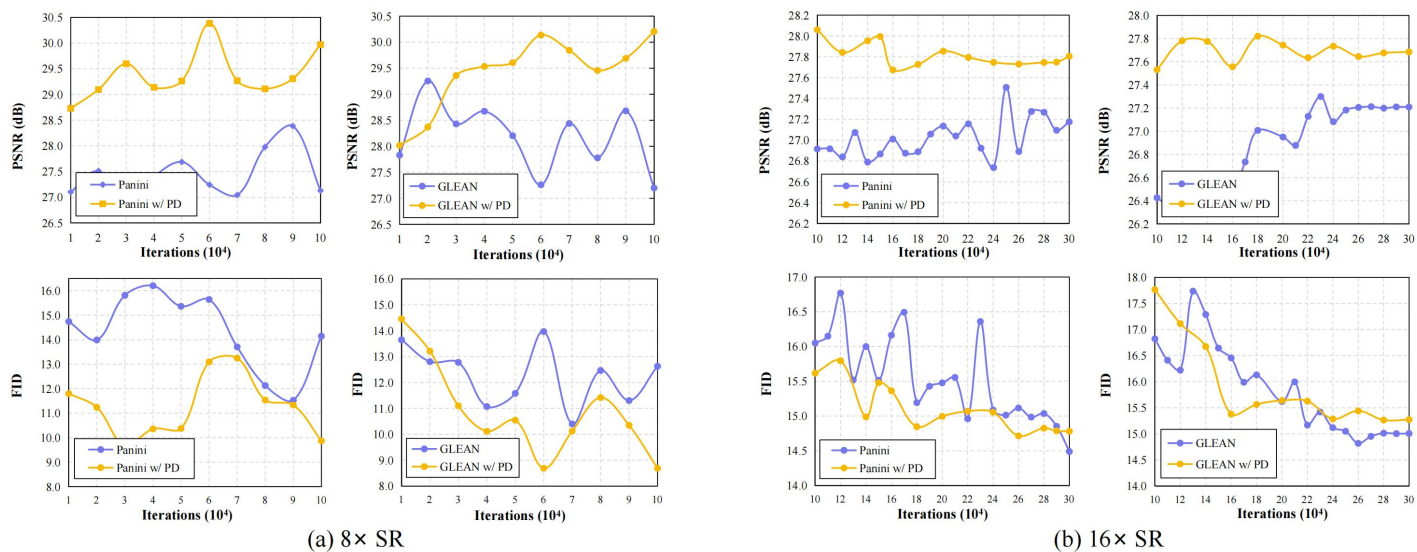


Figure 3: **Convergence curves.** Part (a) for the 8x face SR and (b) for the 16x face SR. With PD, both GLEAN and Panini yield significantly higher PSNR and comparable FID.

Experiment

Dataset	Method	PSNR \uparrow	SSIM \uparrow	FID \downarrow
Face	Panini	27.13	0.729	14.15
	Panini w/ PD	29.97	0.801	9.87
	GLEAN	27.20	0.74	12.63
	GLEAN w/ PD	30.21	0.81	8.69
Cat	Panini	22.36	0.596	129.2
	Panini w/ PD	23.52	0.623	118.9
	GLEAN	22.74	0.588	62.92
	GLEAN w/ PD	22.94	0.597	58.95
Church	Panini	19.27	0.483	67.98
	Panini w/ PD	19.80	0.491	69.20
	GLEAN	19.59	0.485	24.49
	GLEAN w/ PD	19.99	0.500	24.03

Table 2: $8\times$ SR on different categories. The use of PD significantly improves the PSNR, SSIM, and FID in most cases. It is worth noting that PD is parameter-free with negligible computational cost.

Experiment

Method	PSNR \uparrow	SSIM \uparrow	MS-SSIM \uparrow	FID \downarrow
PULSE	21.68	0.676	0.596	42.71
pSp	18.91	0.680	0.526	39.88
GFPGAN	25.17	0.761	0.804	24.34
GPEN	26.07	0.784	0.820	31.89
Panini	27.18	0.758	0.843	14.49
Panini w/ PD	27.81	0.771	0.851	14.78
GLEAN	27.21	0.743	0.843	15.01
GLEAN w/ PD	27.69	0.754	0.848	15.27

Table 3: **Comprehensive comparison on $16\times$ face SR.** We compare Panini and GLEAN and their PD-based versions with state-of-the-art face SR methods. The involvement of PD significantly elevates all consistency metrics, i.e., PSNR, SSIM, and MS-SSIM. We attribute the slight rise of FID to the training stochasticity. Actually, the FID is comparable during training, as can be seen in Fig. [3](#).

Experiment

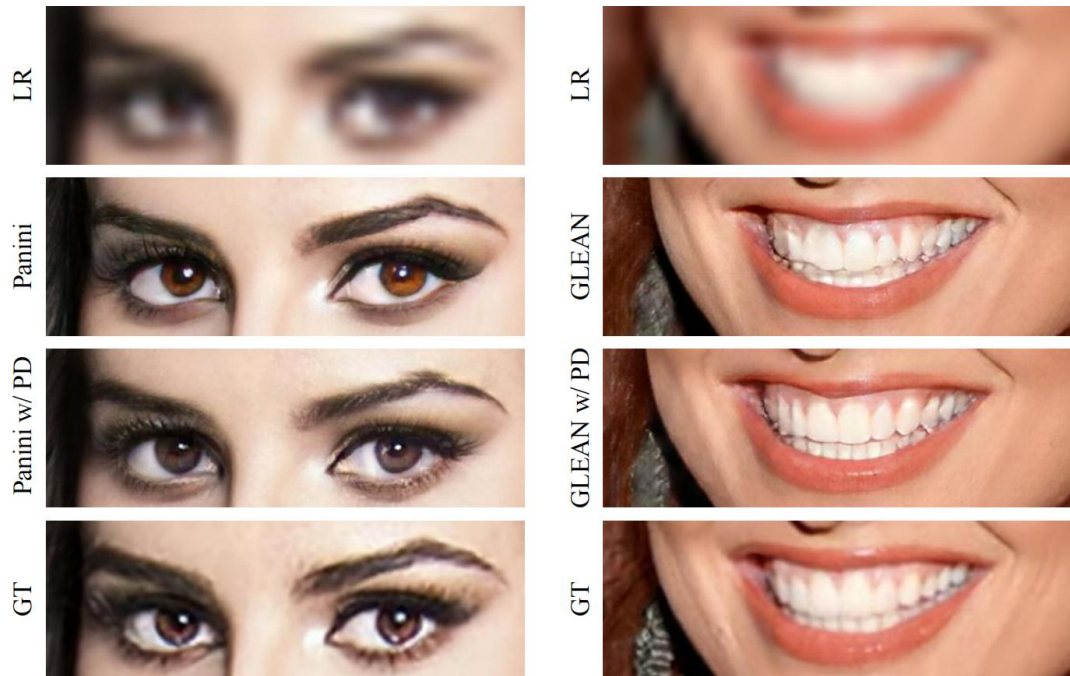


Figure 5: **Qualitative results on $16\times$ face SR.** The use of PD can eliminate color deviation and reduce structural inconsistencies.

Experiment

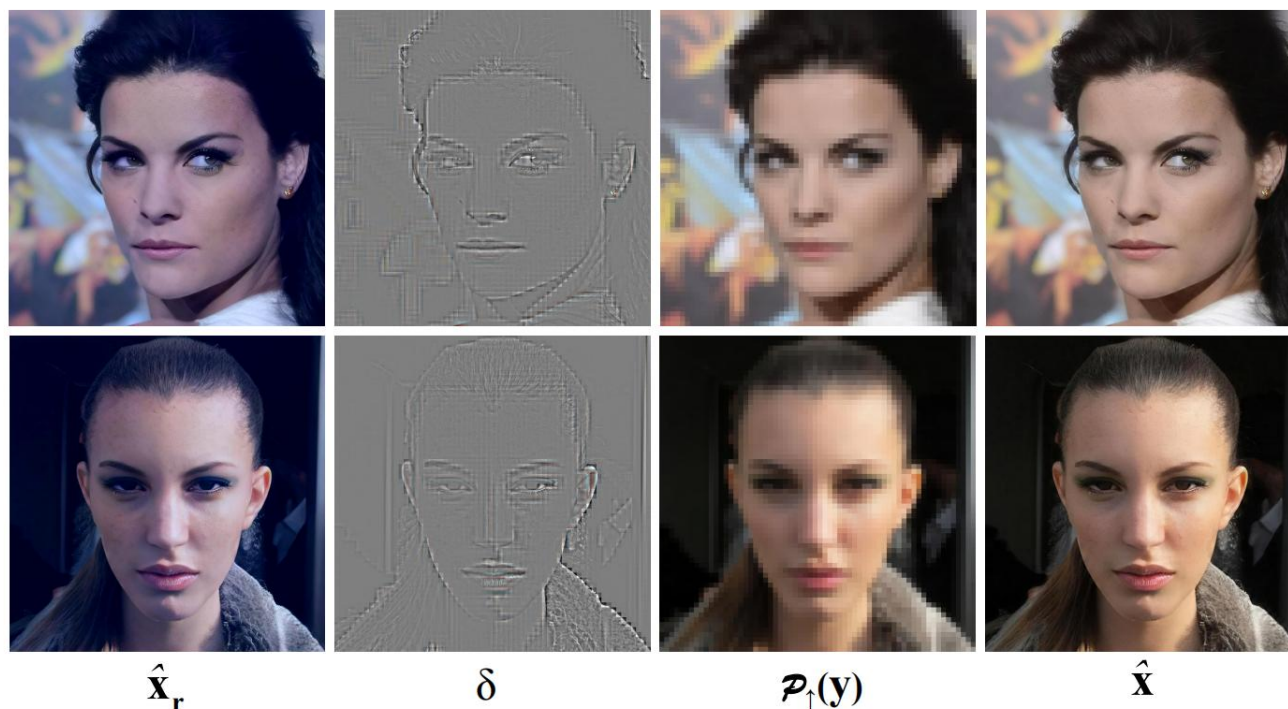


Figure 6: **Visualization of PD.** \hat{x}_r represent the raw prediction of GAN prior network, δ is the high-frequency part of \hat{x}_r . $\mathcal{P}_\uparrow(y)$ denotes the low-frequency contents inherited from LR image. The final result \hat{x} is yielded by adding $\mathcal{P}_\uparrow(y)$ with δ . (**Zoom-in for the best view**)

Experiment

Better generalization results w/o pixel-level loss



Figure 7: **Results on unseen downsamplings.** PDN yields clearer results when facing unseen downsamplings. Here the networks are all trained on $8\times$ bicubic(alias) and tested on $8\times$ bicubic(antialias).

Experiment

Better generalization results w/o pixel-level loss

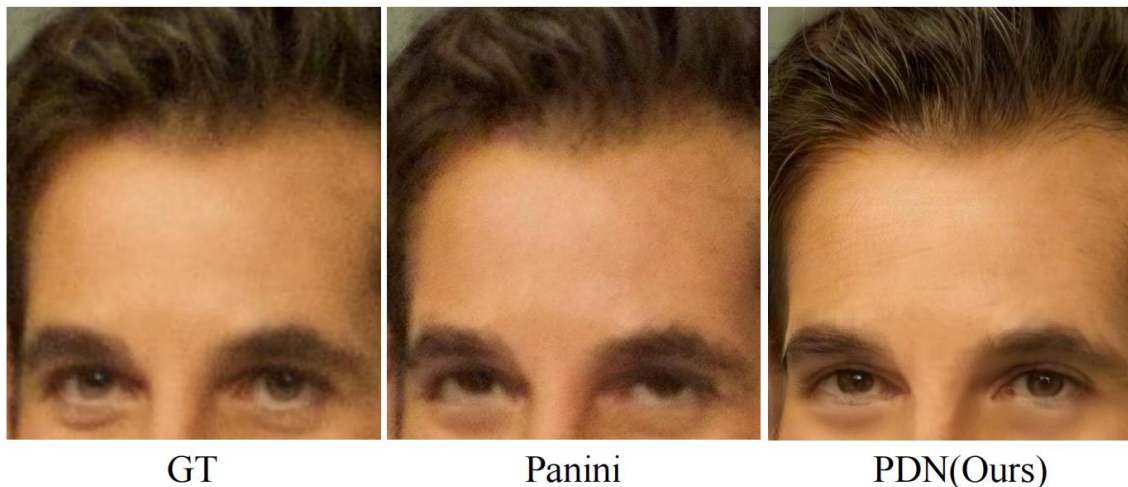
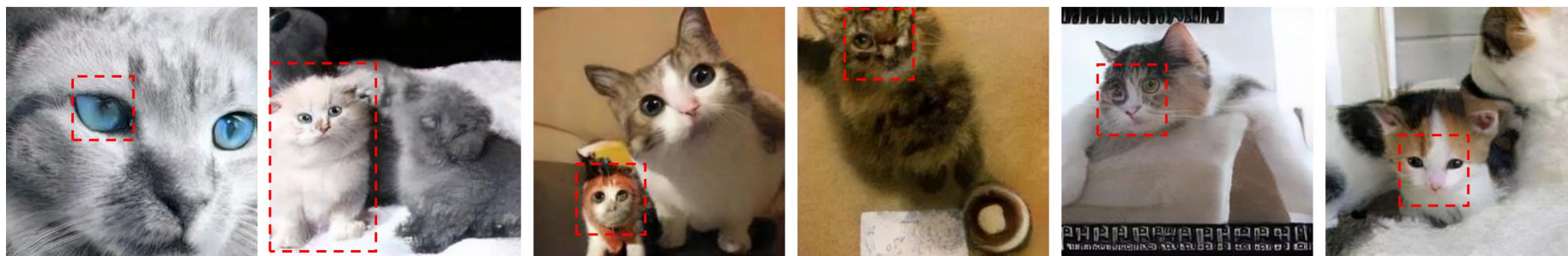


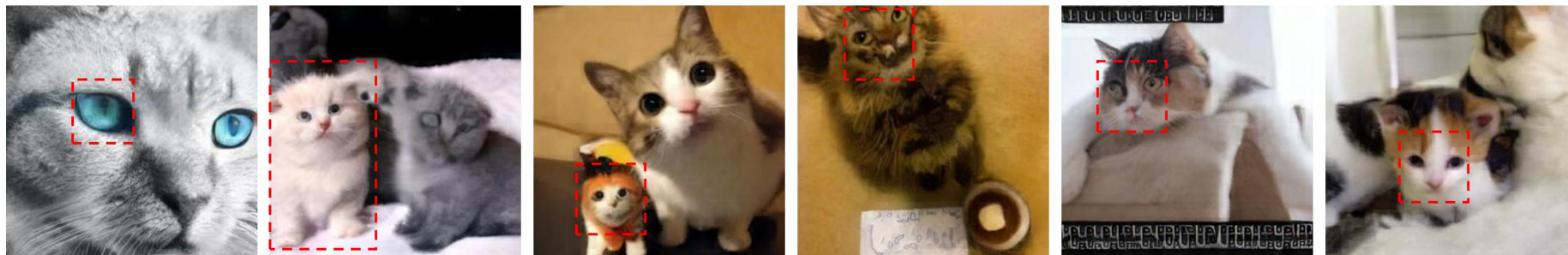
Figure 8: **Results on real-world degradation.** We can see that GLEAN tends to replicate the degradation that GT suffers, while PDN is not affected and tends to generate clear results. Note PDN only uses $16\times$ bicubic(antialias) to synthesize LRs for training, without any simulated degradation.

More results

Panini



Panini w/ PD

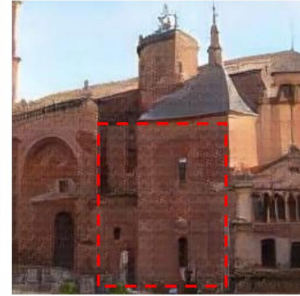
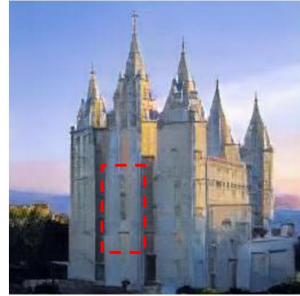
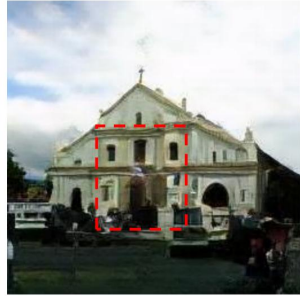
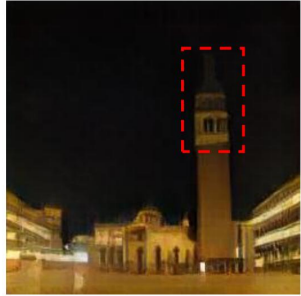
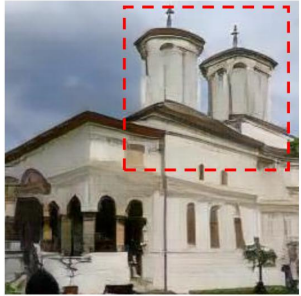


GT

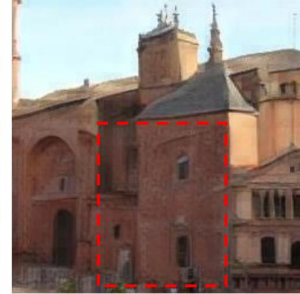
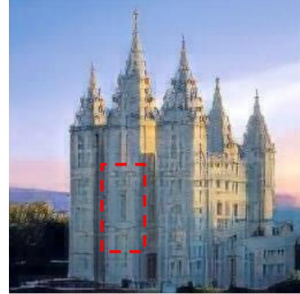
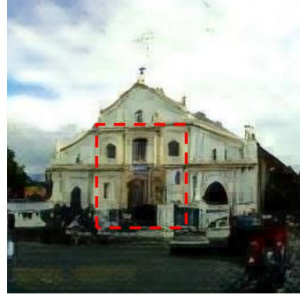
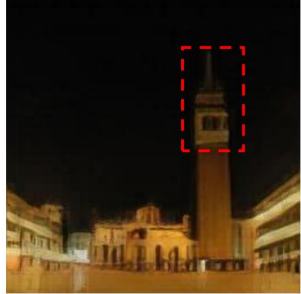
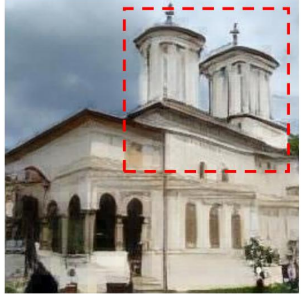


More results

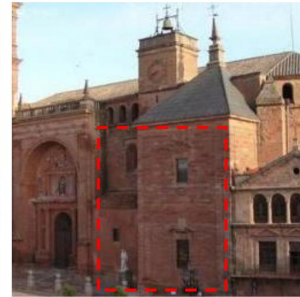
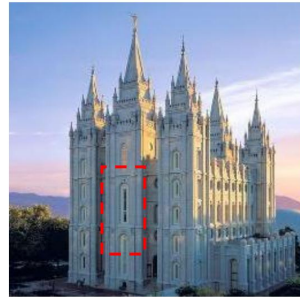
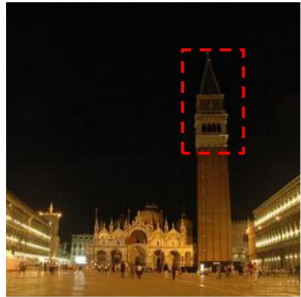
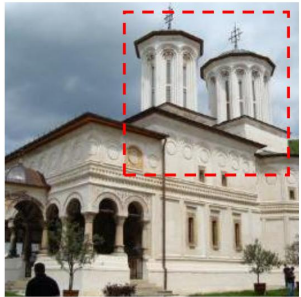
Panini



Panini w/ PD



GT



Conclusion

- A novel method to eliminate inconsistencies for GAN prior based super-resolution networks.
- It can be applied to different backbones, accelerating their training convergence and yielding better consistency.
- It also shows potential in dealing with unseen downsamplings or real-world degradation.
- Hard to deal with hybrid distortions.